







#### **Review Article**

# On the Bogolubov's chain of kinetic equations, the invariant subspaces and the corresponding Dirac type reduction

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#### Abstract

We study a special class of dynamical systems of Boltzmann-Bogolubov and Boltzmann-Vlasov type on infinite dimensional functional manifolds modeling kinetic processes in manyparticle media. Based on geometric properties of the manyparticle phase space we succeded in dual analysing of the infinite Bogolubov hierarchy of manyparticle distribution functions and their Hamiltonian structure. Moreover, we proposed a new approach to invariant reducing the Bogolubov hierarchy on a suitably chosen correlation function constraint and deducing the related modified Boltzmann-Bogolubov kinetic equations on a finite set of multiparticle distribution functions.

## Kinetic equations, their algebraic structure and invariant reductions

#### Introduction

It is well known that the classical Bogolubov-Boltzmann kinetic equations under the condition of manyparticle correlations [1-12] at weak short range interaction potentials describe long waves in a dense gas medium. The same equation, called the Vlasov one, as it was shown by N. Bogolubov [5], describes also exact microscopic solutions of the infinite Bogolubov chain [4] for the manyparticle distribution functions, which was widely studied making use of both classical approaches in [2,6,11,13-23] and in [24-32], making use of the generating Bogolubov functional method and the related quantum current algebra representations.

A.A. Vlasov proposed his kinetic equation [33] for electron-ion plasma, based on general physical reasonings, that in contrast to the short range interaction forces between neutral gas atoms, interaction forces between charged particles slowly decrease with distance, and therefore the motion of each such particle is determined not only by its pair-wise interaction with either particle, yet also by the interaction with the whole ensemble of charged particles. In this case the Bogolubov equation for distribution functions in a domain  $\Lambda \subset \mathbb{R}^3$ 

$$\frac{\partial f_1(z;t)}{\partial t} + \langle \frac{p}{m} | \nabla_x f_1(z;t) \rangle = \int_{T^*(\Lambda)} dz' \{ f_2(z,z';t), V(x-x') \}^{(2)}, \tag{1.1}$$

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where  $z := (x, p) \in T^*(\Lambda), t \in \mathbb{R}_+$  is the temporal evolution parameter,  $\{\cdot, \cdot\}^{(m)}$  denotes the canonical Poisson bracket [6,33,34] on the product  $T^*(\Lambda)^m, m \in \mathbb{N}$ , and  $V(x-x'), x, x' \in \Lambda$ , is an interparticle interaction potential, – reduces to the Vlasov equation if to put in (1.1)

$$f_2(z, z'; t) = f_1(z; t) f_1(z'; t),$$
(1.2)

that is to assume that the two-particle correlation function [2,3,11,23] vanishes:

$$g_{2}(z,z';t) = f_{2}(z,z';t) - f_{1}(z;t)f_{1}(z';t) = 0$$
(1.3)

for all  $z, z' \in T^*(\Lambda)$  and  $t \in \mathbb{R}$ . Then one easily obtains from (1.1) that

$$\frac{\partial f_1(z;t)}{\partial t} + \langle \frac{p}{m} | \nabla_x f_1(z;t) \rangle = \langle \frac{\partial f_1(z;t)}{\partial p} | \nabla_x \int_{T^*(\Lambda)} dz' V(x-x') f_1(z';t) \rangle$$
(1.4)

for all  $z \in T^*(\Lambda)$  and  $t \in \mathbb{R}_+$ . Remark here that the equation (1.4) is reversible under the time reflection  $\mathbb{R}_- \ni -t \rightleftharpoons t \in \mathbb{R}_+$ , thus it is obvious that it can not describe thermodynamically stable limiting states of the particle system in contrast to the classical Bogolubov-Boltzmann kinetic equations [1,2,4,6,11,24,27], being a priori time nonreversible owing to the choice of boundary conditions in the correlation weakening form. This means that in spite of the Hamiltonicity of the Bogolubov chain for the distribution functions, the Bogolubov-Boltzmann equation a priori is not reversible. It is also evident that the condition (1.3) does not break the Hamiltonicity – the equation (1.4) is Hamiltonian with respect to the following Lie-Poisson-Vlasov bracket:

$$\{\{a(f),b(f)\}\} := \int_{T^*(\Lambda)} dz f(z) \{grada(f)(z), gradb(f)(z)\}^{(1)}, \tag{1.5}$$

 $\text{where } \operatorname{grad}(\cdot) \coloneqq \delta(\cdot) \, / \, \delta f, f \in D(T^*(\Lambda)) \coloneqq M_{f_1}, \text{ respectively } a, b \in D(M_{f_1}) \text{ are smooth functionals on the functional manifold } define the following problem of the fo$  $M_{f_1}$ , consisting of functions fast decreasing at the boundary  $\partial \Lambda$  of the domain  $\Lambda \subset \mathbb{R}^3$ . The statement above easily ensues from the following proposition.

**Proposition 1.1** Let  $M_{\mathcal{F}}$  denote a set of many-particle distribution functions. Then the classical Bogolubov-Poisson bracket [4,18,24,25] on the functional space  $D(M_{\mathcal{F}})$  reduces invariantly on the subspace  $D(M_{f_1}) \subset D(M_{\mathcal{F}})$  to the Lie-Poisson-Vlasov bracket (1.5).

Concerning the general case when we are work with an innite Bogolubov chain of kinetic equations on the many-particle distribution functions and forced to break it at some place, numbered by some natural number  $N \in N$ ; the usual approaches always give rise to the resulting inconsistency [3,5] of the chain and, as a result, to the nonphysical solutions. The most successful approach to obtaining the Boltzmann kinetic equation for the one-particle distribution function was suggested still many years ago by N. Bogolubov [1,2], based on the e/ective application of the so called weak correlation condition. So far, to the regret, this approach, being conjugated with the complex problem of solving functional equations, also gives rise to the inconsistency of the higher order kinetic equations. Nonetheless, being inspired by former studies [6, 16, 11] of these problems, based on the geometrical interpretation of the Bogolubov kinetic equations chain, we devised a new functional analytic approach to constructing its compatible reduction a priori free of any unphysical consequences. We also succeeded in constructing a reduced set of kinetic equations, based on a suitably devised Dirac type invariant reduction scheme of the corresponding many-particle Lie-Poisson phase space. The approach to solving this problem and its di/erent consequences will be analyzed in more detail in sections to follow below.

### The Lie-Poisson-Vlasov bracket: Lie-algebraic approach

The bracket expression (1.5) allows a slightly different Lie-algebraic interpretation, based on considering the functional space  $D(M_{f_1})$  as a Poissonian manifold, related with the canonical symplectic structure on the diffeomorphism group  $Diff(\Lambda)$  of the domain  $\Lambda \subset \mathbb{R}^3$ , first described [35,36] still in 1887 by Sophus Lie. Namely, the following classical theorem holds.

**Theorem 1.2** The Lie-Poisson bracket at point  $(\mu; \eta) \in T^*_{\eta}(Diff(\Lambda))$  on the coadjoint space  $T^*_{\eta}(Diff(\Lambda)), \eta \in Diff(\Lambda)$ , is equal to the expression

$$\{f,g\}(\mu) = (\mu \mid [\delta g(\mu) / \delta \mu, \delta f(\mu) / \delta \mu])_c \tag{1.6}$$

for any smooth right-invariant functionals  $f, g \in C^{\infty}(T_n^*(Diff(\Lambda)); \mathbb{R})$ .

 $(\mu | a)_c, (\mu | b)_c$ classical definition [33-37] of the Poisson bracket smooth functions  $\in C^{\infty}(T_n^*(Diff(\Lambda));\mathbb{R}), a,b \in diff(\Lambda) \simeq T_n(Diff(\Lambda))$  on the symplectic space  $T_{\eta}^*(Diff(\Lambda))$ , it is easy to calculate that

$$\{\mu(a), \mu(b)\} := \delta\alpha(X_a, X_b) =$$

$$= X_a(\alpha \mid X_b)_c - X_b(\alpha \mid X_a)_c - (\alpha \mid [X_a, X_b])_c,$$
(1.7)

where  $X_a := \delta(\mu \mid a)_c / \delta\mu = a \in diff(\Lambda), X_b := \delta(\mu \mid b)_c / \delta\mu = b \in diff(\Lambda)$ . Since the expressions  $X_a(\alpha \mid X_b)_c = 0$  and  $X_b(\alpha \mid X_a)_c = 0$  owing the right-invariance of the vector fields  $X_a, X_b \in T_\eta(Diff(\Lambda))$ , the Poisson bracket (1.7) transforms into

$$\{ (\mu | a)_{c}, (\mu | b)_{c} \} = -(\alpha | [X_{a}, X_{b}])_{c} =$$

$$= (\mu | [b, a])_{c} = (\mu | [\delta(\mu | b)_{c} / \delta\mu, \delta(\mu | a)_{c} / \delta\mu])_{c}$$
(1.8)

for all  $(\mu;\eta) \in T_n^*(Diff(\Lambda)) \cong diff^*(\Lambda)$ , and any  $a,b \in diff(\Lambda)$ . The Poisson bracket (1.8) is easily generalized to

$$\{f,g\}(\mu) = (\mu | [\delta g(\mu) / \delta \mu, \delta f(\mu) / \delta \mu])_c \tag{1.9}$$

for any smooth functionals  $f, g \in C^{\infty}(diff^*(\Lambda); \mathbb{R})$ , finishing the proof.

Concerning our special problem of describing evolution equations for one-particle distribution functions, we will consider the one particle cotangent space  $T^*(\Lambda)$  over a domain  $\Lambda \subset \mathbb{R}^3$  and the canonical Poisson bracket  $\{\cdot,\cdot\} := \{\cdot,\cdot\}^{(1)}$  on  $T^*(\Lambda)$ , for which, by definition, for any  $f, g \in M_f$ 

$$\{f,g\}(z) := \langle \frac{\partial f}{\partial p} | \frac{\partial g}{\partial x} \rangle - \langle \frac{\partial g}{\partial p} | \frac{\partial f}{\partial x} \rangle, \tag{1.10}$$

where  $z = (x, p) \in T^*(\Lambda)$ . Denote now by  $\mathcal{G} := (M_{f_1}; \{\cdot, \cdot\})$  the related functional Lie algebra and  $\mathcal{G}^*$  its adjoint space with respect to the standard bilinear symmetric form  $(\cdot|\cdot):M_{f_1}\times M_{f_1}\to\mathbb{R}$  on the product  $M_{f_1}\times M_{f_1}$ , where

$$(f \mid g) := \int_{T^*(\Lambda)} f(z)g(z)dz. \tag{1.11}$$

The constructed Lie algebra  $\mathcal G$  with respect to the bilinear symmetric form (1.11) proves to be metrized, that is  $\mathcal G \simeq \mathcal G^*$  and

$$(\{f,g\} \mid h) = (f \mid \{g \mid h\}) \tag{1.12}$$

for any f,g and  $h \in \mathcal{G}$ . If  $\gamma \in D(\mathcal{G}^*)$  is a smooth functional on  $\mathcal{G}^*$ , its gradient  $grad\gamma(f) \in \mathcal{G}$  at point  $f \in \mathcal{G}^*$  is naturally defined via the limiting expression

$$(g \mid grad\gamma(f)) := \frac{d}{d\varepsilon} \gamma(f + \varepsilon g) \bigg|_{\varepsilon = 0}$$
(1.13)

for arbitrary element  $g \in \mathcal{G}^*$ . Define now the Poisson structure  $\{\{\cdot,\cdot\}\}: \mathcal{G}^* \times \mathcal{G}^* \to \mathbb{R}$  by means of the standard Lie-Poisson [9,33,34-36,38,39] expression:

$$\{\{\gamma,\mu\}\} := (f \mid \{grad\gamma(f), grad\gamma(f)\})$$
(1.14)

for arbitrary functionals  $\gamma, \mu \in D(\mathcal{G}^*)$ . It is evident that the expression (1.14) identically coincides with the Poisson bracket (1.5). Consider a functional  $\gamma \in D(\mathcal{G}^*)$  and the related coadjoint action of the element  $grad \gamma(f) \in \mathcal{G}$  at a fixed element  $f := f_1 \in \mathcal{G}^*$ :



$$\partial f_1 / \partial t := ad_{\operatorname{grad}_{Y}(f_1)}^* f_1, \tag{1.15}$$

where  $t \in \mathbb{R}$  is the corresponding evolution parameter. It is easy observe that

$$\partial f_1 / \partial t = \{ \{ \gamma, f_1 \} \} \tag{1.16}$$

is a Hamiltonian equation with the functional  $\gamma \in D(\mathcal{G}^*)$  taken as its Hamiltonian, being simultaneously equivalent to the following canonical Hamiltonian flow:

$$\partial f_1 / \partial t = \{ f_1, \operatorname{grad} \gamma(f_1) \}, \tag{1.17}$$

if to choose as a Hamiltonian the following functional

$$\gamma(f_1) := \int_{T^*(\Lambda)} dz_1 \frac{p_1^2}{2m} f_1(z_1) + \frac{1}{2} \int_{T^*(\Lambda)^2} dz_1 dz_2 V(x_1 - x_2) f_1(z_1) f_1(z_2), \tag{1.18}$$

where  $V(x_1 - x_2)$  is a two-particle interaction potential,  $x_1, x_2 \in \Lambda$ . It is easy to observe here that the Hamiltonian (1.18) is obtained from the corresponding classical Bogolubov Hamiltonian expression

$$\mathcal{H}(\mathcal{F}) := \int_{T^*(\Lambda)} dz_1 \frac{p_1^2}{2m} f_1(z_1) + \frac{1}{2} \int_{T^*(\Lambda)^2} dz_1 dz_2 V(x_1 - x_2) f_2(z_1, z_2), \tag{1.19}$$

where  $\mathcal{F} = (f_{1,}f_{2},...) \in M_{\mathcal{F}}$  denotes an infinite vector from the space  $M_{\mathcal{F}} \coloneqq \prod_{j \in \mathbb{N}} M_{f_{j}}$  of multiparticle distribution functions, and if to impose on it the constraint (1.2). Thus we have stated the following proposition.

**Proposition 1.3** The Boltzmann-Vlasov kinetic equation (1.4) is a Hamiltonian system on the functional manifold  $\mathcal{G}^* \simeq \mathcal{G} = (M_f; \{\cdot, \cdot\})$ with respect to the canonical Lie-Poisson structure (1.14) with Hamiltonian (1.18). As a consequence, the flow (1.4) is time reversible.

#### Boltzmann-Vlasov kinetic equations and microscopic exact solutions

Proposition 1.1, stated above, claims that the Boltzmann-Vlasov equation (1.4) is a suitable reduction of the whole Bogolubov chain upon the invariant functional subspace  $M_{f_i} \subset M_{\mathcal{F}}$ . Moreover, this invariance in no way should be compatible a priori [5,19,21,24,25,27] with the other kinetic equations from the Bogolubov chain, and can be even contradictory. Nonetheless, as it was stated [5] by N. Bogolubov, namely owing to this invariance of the subspace  $M_{f_1} \subset M_{\mathcal{F}}$  the Boltzmann-Vlasov equation (1.4) in the case of the Boltzmann-Enskog hard sphere approximation of the inter-particle potential possesses exact microscopical solutions which are compatible with the whole hierarchy of the Bogolubob kinetic equations. The latter is, obviously, equivalent to its Hamiltonicity on the manifold  $M_{f_1}$  with respect to the Lie-Poisson bracket (1.14). The Boltzmann-Enskog kinetic equation [3,5,11,12,23] equals

$$\frac{\partial f_1(z;t)}{\partial t} + \langle \frac{p}{m} | \nabla_x f_1(z;t) \rangle =$$

 $=a^{2}\int_{\mathbb{S}^{2}}dn\int_{\mathbb{S}^{3}}dp^{'}\langle p^{'}|n\rangle\langle \frac{\tilde{p}^{'}}{m}|n\rangle\Big[f_{2}(x,\tilde{p};x+an,\tilde{p}';t)-f_{2}(x,p;x-an,p';t)\Big]$ (1.20)

where  $\tilde{p} := p + n \langle p' - p \mid n \rangle$ ,  $\tilde{p}' := p - n \langle p' - p \mid n \rangle$ , a > 0 a particle diameter,  $n \in \mathbb{S}^2$  a unit vector,  $\langle n \mid n \rangle = 1$ , and, by definition,  $f_2(z,z^{'};t)=0$  for all  $z,z^{'}\in T^*(\Lambda),\ t\in\mathbb{R},$  satisfying the condition  $||z-z^{'}|| < a$ . The equation (1.20) easily reduces to the Vlasov-Enskog equation



$$\frac{\partial f_1(z;t)}{\partial t} + \langle \frac{p}{m} | \nabla_x f_1(z;t) \rangle = J_{V-E}(f),$$

$$J_{V-E}(f) = a^2 \int_{\mathbb{S}^2} dn \int_{\mathbb{E}^3} dp' \langle p' | n \rangle \langle \frac{\tilde{p}'}{m} | n \rangle \times$$

$$\times \left[ f_{1}(x,\tilde{p};t)f_{1}(x+an,\tilde{p}';t) - f_{1}(x,p;t)f_{1}(x-an,p';t) \right]$$
(1.21)

for all  $(z;t) \in T^*(\Lambda) \times \mathbb{R}$  owing to its Hamiltonicity on the space  $M_{f_1} \subset M_{\mathcal{F}}$ . If in addition there exists a nontrivial interparticle potential, the equation above is naturally generalized to the kinetic equation

$$\frac{\partial f_1(z;t)}{\partial t} + \langle \frac{p}{m} | \nabla_x f_1(z;t) \rangle = J_{V-E}(f) +$$

$$+ \int_{T^*(\Lambda)} dz' \{ f_1(z;t) f_1(z';t), V(x-x') \}^{(2)},$$
(1.22)

which remains to be Hamiltonian on  $M_{f_1}$  and possesses, in particular, the following exact singular solution:

$$f_1(z;t) = \sum_{j=1,N} \delta(z - z_j(t)), \tag{1.23}$$

where  $z_i(t) \in T^*(\Lambda)$ ,  $j = \overline{1, N}$ , - phase space coordinates in  $T^*(\Lambda)^N$  of  $N \in \mathbb{N}$  interacting particles in the domain  $\Lambda \subset \mathbb{R}^3$ . Specified above the Hamiltonicity problem and the existence of exact solutions to the Botzmann-Vlasov kinetic equation (1.22) is deeply related to that of describing correlation functions [2,11,23], suitably breaking the infinite Bogolubov chain [2,4,11,24,30,31] of manyparticle distribution functions. Namely, if to introduce manyparticle correlation functions [2,11,23] for related Bogolubov distribution

$$\begin{split} g_1(z_1) &= 0, g_2(z_1, z_2) = f_2(z_1, z_2) - f_1(z_1) f_1(z_2), \\ g_3(z_1, z_2, z_3) &= f_3(z_1, z_2, z_3) - f_1(z_1) f_1(z_2) f_1(z_3) - f_1(z_1) g_2(z_2, z_3) - \\ -f_1(z_2) g_2(z_3, z_1) - f_1(z_3) g_2(z_1, z_2), \ldots, \end{split}$$

where  $z_i \in T^*(\Lambda)$ ,  $j \in N$ , then the Vlasov equation (1.22) is obtained from the Bogolubov hierarchy at n=1 and  $g_2(z_1,z_2)=0$  for all  $z_1, z_2 \in T^*(\Lambda)$ .

As it was mentioned above, the constraint imposed on the infinite Bogolubov hierarchy is compatible with its Hamiltonicity. Yet in many practical cases this closedness procedure by means of imposing the conditions like

$$g_{m+1}(z_1, z_2, ..., z_{m+1}) = 0 ag{1.25}$$

for all  $z \in T^*(\Lambda)$ ,  $s = \overline{1, m+1}$  at some fixed  $m \ge 2$  gives rise to some serious dynamical problems related with its mathematical correctness. Namely, if to close this way the infinite Bogolubov chain of kinetic equations on manyparticle distribution functions, one easily checks that the imposed constraint (1.25) does not persists in time subject to the evolution of the distribution functions  $f_i(z_1, z_2, ..., z_i), z_i \in T^*(\Lambda), j = \overline{1, m}$ . This menas that these naively reduced kinetic equations are written down somehow incorrectly, as the reduced functional submanifold  $M_{\mathcal{F}}^{(m)} := \{ \mathcal{F} \in M_{\mathcal{F}} : g_{m+1} = 0 \}$  should remain invariant in time. To dissolve this problem we are forced to consider the whole Bogolubov hierarchy of kinetic equationas on multiparticle distribution functions as a Hamiltonian

system on the functional manifold  $M_{\mathcal{F}}$  and correctly reduce it on the constructed above functional submanifold  $M_{\mathcal{F}}^{(m)} \subset M_{\mathcal{F}}$  via the classical Dirac type [1, 3, 6, 19, 36] procedure. The kinetic equations obtained this way by means of the reduced Lie-Poisson-Bogolubov structure will evidently differ from those naively obtained by means of the direct substitution of the imposed constraint (1.25) into the Bogolubov chain of kinetic equations, and in due course will conserve the functional submanifold  $M_{\mathcal{F}}^{(m)} \subset M_{\mathcal{F}}$  invariant.

### The invariant reduction of the Bogolubov distribution functions chain

Consider the constructed before Hamiltonian functional  $\mathcal{H}(\mathcal{F}) \in D(M_{\mathcal{F}})$  (1.19)

$$\mathcal{H}(\mathcal{F}) = \int_{T^*(\Lambda)} dz_1 \frac{p_1^2}{2m} f_1(z_1) + \frac{1}{2} \int_{T^*(\Lambda)^2} dz_1 dz_2 V(x_1 - x_2) f_2(z_1, z_2)$$
(1.26)

and calculate the evolution of the distribution functions vector  $\mathcal{F} \in M_{\mathcal{F}}$  under the simplest constraint (1.25) at m = 1, that is

$$g_2(z_1, z_2) = f_2(z_1, z_2) - f_1(z_1) f_1(z_2) = 0$$
(1.27)

for all  $z_1, z_2 \in T^*(\Lambda)$ . To perform this reduction on  $M_{\mathcal{F}}^{(1)} \subset M_{\mathcal{F}}$  we need [39-43] to constraint the  $\lambda$ -extended Hamiltonian expression

$$\mathcal{H}_{\lambda}(\mathcal{F}) := \mathcal{H}(\mathcal{F}) + \frac{1}{2} \int_{T^*(\Lambda)^2} dz_1 dz_2 \lambda(z_1, z_2) \left[ f_2(z_1, z_2) - f_1(z_1) f_1(z_2) \right]$$
(1.28)

for some smooth function  $\lambda \in D(T^*(\Lambda)^2)$  and next to determine it from the submanifold  $M_{\mathcal{F}}^{(1)}$  invariance condition

$$\frac{\partial g_2(z_1, z_2)}{\partial t} = \{\{\mathcal{H}_{\lambda}(\mathcal{F}), g_2(z_1, z_2)\}\} =$$

$$=\frac{\partial f_2(z_1, z_2)}{\partial t} - \frac{\partial f_1(z_1)}{\partial t} f_1(z_2) - f_1(z_1) \frac{\partial f_1(z_2)}{\partial t} = 0$$
(1.29)

for all  $z_1, z_2 \in T^*(\Lambda)$  and  $t \in \mathbb{R}$ . To calculate effectively the condition (1.29) let us first calculate the evolutions for distribution functions  $f_1$  and  $f_2 \in M_{\mathcal{F}}$ :

$$\frac{\partial f_1(z_1)}{\partial t} = \left\{ \left\{ \mathcal{H}_{\lambda}(\mathcal{F}), f_1(z_1) \right\} \right\} = \left\{ f_1(z_1), \frac{\delta \mathcal{H}_{\lambda}(\mathcal{F})}{\delta f_1(z_1)} \right\}^{(1)} + \tag{1.30}$$

$$+\int_{T^*(\Lambda)} dz_2 \left\{ f_2(z_1, z_2), \frac{\delta \mathcal{H}_{\lambda}(\mathcal{F})}{\delta f_2(z_1, z_2)} \right\}^{(1)},$$

and

$$\frac{\partial f_2(z_1, z_2)}{\partial t} = \left\{ \left\{ \mathcal{H}_{\lambda}(\mathcal{F}), f_2(z_1, z_2) \right\} \right\} = \left\{ f_2(z_1, z_2), \frac{\delta \mathcal{H}_{\lambda}(\mathcal{F})}{\delta f_1(z_1)} + \frac{\delta \mathcal{H}_{\lambda}(\mathcal{F})}{\delta f_1(z_2)} \right\}^{(2)} + \frac{\delta \mathcal{H}_{\lambda}(\mathcal{F})}{\delta f_1(z_2)} + \frac{\delta \mathcal{H}_{\lambda}(\mathcal{F})}{\delta f_1(z_2)} \right\}^{(2)} + \frac{\delta \mathcal{H}_{\lambda}(\mathcal{F})}{\delta f_1(z_2)} +$$

$$+\left\{f_{2}(z_{1},z_{2}),\frac{\mathcal{SH}_{\lambda}(\mathcal{F})}{\mathcal{S}f_{2}(z_{1},z_{2})}\right\}^{(2)}+\int_{T^{*}(\Lambda)}dz_{3}\left\{f_{3}(z_{1},z_{2},z_{3}),\frac{\mathcal{SH}_{\lambda}(\mathcal{F})}{\mathcal{S}f_{2}(z_{1},z_{3})}+\frac{\mathcal{SH}_{\lambda}(\mathcal{F})}{\mathcal{S}f_{2}(z_{2},z_{3})}\right\}^{(2)},$$
(1.31)

which can be rewritten equivalently as follows:



$$\frac{\partial f_1(z_1)}{\partial t} = -\langle \frac{\partial f_1(z_1)}{\partial p_1} | \int_{T^*(\Lambda)} dz_2 \frac{\partial \lambda(z_1, z_2)}{\partial x_1} f_1(z_2) -$$
(1.32)

$$-\langle \frac{p_1}{m} - \int_{T^*(\Lambda)} dz_2 \frac{\partial \lambda(z_1, z_2)}{\partial p_1} f_1(z_2) | \frac{\partial f_1(z_1)}{\partial x_1} \rangle +$$

$$+\frac{1}{2}\int_{T^*(\Lambda)}dz_2\langle \frac{\partial}{\partial x_1}[V(x_1-x_2)+\lambda(z_1,z_2)]|\frac{\partial f_2(z_1,z_2)}{\partial p_1}\rangle -$$

$$-\frac{1}{2}\int_{T^*(\Lambda)}dz_2\langle\frac{\partial\lambda(z_1,z_2)}{\partial p_1}|\frac{\partial f_2(z_1,z_2)}{\partial x_1}\rangle$$

and

$$\begin{split} \frac{\partial f_2(z_1,z_2)}{\partial t} &= -\langle \frac{\partial f_2(z_1,z_2)}{\partial p_1} | \int_{T^*(\Lambda)} dz_2 \frac{\partial \lambda(z_1,z_2)}{\partial x_1} f_1(z_2) \rangle - \\ &-\langle \frac{\partial f_2(z_1,z_2)}{\partial p_2} | \int_{T^*(\Lambda)} dz_1 \frac{\partial \lambda(z_1,z_2)}{\partial x_2} f_1(z_1) \rangle - \\ &-\langle \frac{\partial f_2(z_1,z_2)}{\partial x_1} | \frac{p_1}{m} - \int_{T^*(\Lambda)} dz_2 \frac{\partial \lambda(z_1,z_2)}{\partial p_1} f_1(z_2) \rangle - \\ &-\langle \frac{\partial f_2(z_1,z_2)}{\partial x_2} | \frac{p_2}{m} - \int_{T^*(\Lambda)} dz_1 \frac{\partial \lambda(z_1,z_2)}{\partial p_2} f_1(z_1) \rangle + \\ &+ \frac{1}{2} \langle \frac{\partial f_2(z_1,z_2)}{\partial p_1} | \frac{\partial}{\partial x_1} [V(x_1-x_2) + \lambda(z_1,z_2)] \rangle + \\ &+ \frac{1}{2} \langle \frac{\partial f_2(z_1,z_2)}{\partial p_2} | \frac{\partial}{\partial x_2} [V(x_1-x_2) + \lambda(z_1,z_2)] \rangle - \\ &- \frac{1}{2} \langle \frac{\partial f_2(z_1,z_2)}{\partial x_1} | \frac{\partial \lambda(z_1,z_2)}{\partial p_1} \rangle - \frac{1}{2} \langle \frac{\partial f_2(z_1,z_2)}{\partial x_2} | \frac{\partial \lambda(z_1,z_2)}{\partial p_2} \rangle + \\ &+ \frac{1}{2} \langle \int_{T^*(\Lambda)} dz_3 \frac{\partial f_3(z_1,z_2,z_3)}{\partial p_1} | \frac{\partial}{\partial x_1} [V(x_1-x_3) + \lambda(z_1,z_3)] \rangle + \\ &+ \frac{1}{2} \langle \int_{T^*(\Lambda)} dz_3 \frac{\partial f_3(z_1,z_2,z_3)}{\partial p_2} | \frac{\partial}{\partial x_2} [V(x_2-x_3) + \lambda(z_2,z_3)] \rangle - \\ &- \frac{1}{2} \langle \int_{T^*(\Lambda)} dz_3 \frac{\partial f_3(z_1,z_2,z_3)}{\partial x_3} | \frac{\partial}{\partial x_1} [V(x_2-x_3) + \lambda(z_2,z_3)] \rangle - \\ &- \frac{1}{2} \langle \int_{T^*(\Lambda)} dz_3 \frac{\partial f_3(z_1,z_2,z_3)}{\partial x_3} | \frac{\partial}{\partial x_1} [V(x_2-x_3) + \lambda(z_2,z_3)] \rangle - \\ &- \frac{1}{2} \langle \int_{T^*(\Lambda)} dz_3 \frac{\partial f_3(z_1,z_2,z_3)}{\partial x_3} | \frac{\partial}{\partial x_1} [V(x_1-x_2) - \frac{1}{2} \langle \int_{T^*(\Lambda)} dz_3 \frac{\partial f_3(z_1,z_2,z_3)}{\partial x_3} | \frac{\partial}{\partial x_2} [V(x_2-x_3) + \lambda(z_2,z_3)] \rangle - \\ &- \frac{1}{2} \langle \int_{T^*(\Lambda)} dz_3 \frac{\partial f_3(z_1,z_2,z_3)}{\partial x_3} | \frac{\partial}{\partial x_1} [V(x_1-x_2) - \frac{1}{2} \langle \int_{T^*(\Lambda)} dz_3 \frac{\partial}{\partial x_2} [V(x_2-x_3) + \lambda(z_2,z_3)] \rangle - \\ &- \frac{1}{2} \langle \int_{T^*(\Lambda)} dz_3 \frac{\partial}{\partial x_1} [Z(x_1,x_2,z_3)] \rangle - \frac{\partial}{\partial x_1} [Z(x_1,x_2,z_3)] \rangle - \frac{\partial}{\partial x_2} [Z(x_1,x_2,z_3)] \rangle - \frac{\partial}{\partial x_1} [Z(x_1,x_2,z_3)] \rangle - \frac{\partial}{\partial x_2} [Z(x_1,x_2,z_3)] \rangle - \frac{\partial}{\partial x_2} [Z(x_1,x_2,z_3)] \rangle - \frac{\partial}{\partial x_1} [Z(x_1,x_2,z_3)] \rangle - \frac{\partial}{\partial x_2} [Z(x_1,x_2,z_3)] \rangle - \frac{\partial}{\partial x_1} [Z(x_1,x_2,z_3)] \rangle - \frac{\partial}{\partial x_2} [Z(x_1,x_2,z_3)] \rangle - \frac{\partial$$

Having now substituted temporal derivatives (1.32) and (1.33) into the equality (1.29) in their explicit form, one obtains the following functional relationship:



$$\frac{1}{2} \langle f_1(z_2) \frac{\partial f_1(z_1)}{\partial p_1} | \frac{\partial}{\partial x_1} (V(x_1 - x_2) + \lambda(z_1, z_2) - \int_{T^*(\Lambda)} dz_3 f_1(z_3) [V(x_1 - x_3) + \lambda(z_1, z_3)] \rangle + 
+ \frac{1}{2} \langle f_1(z_1) \frac{\partial f_1(z_2)}{\partial p_2} | \frac{\partial}{\partial x_2} (V(x_2 - x_1) + \lambda(z_2, z_1) - \\
- \int_{T^*(\Lambda)} dz_3 f_1(z_3) [V(x_2 - x_3) + \lambda(z_2, z_3)] \rangle = 0,$$
(1.34)

which is satisfied iff

$$\lambda(z_1, z_2) = -V(x_1 - x_2) \tag{1.35}$$

for all  $z_1, z_2 \in T^*(\Lambda)$ . Taking into account the result (1.35), one easily obtains from the equation (1.32) the invariantly reduced on the submanifold  $M_{\mathcal{F}}^{(1)} \subset M_{\mathcal{F}}$  kinetic equation on the one-particle distribution function:

$$\frac{\partial f_1(z_1)}{\partial t} + \langle p_1 / m \mid \frac{\partial f_1(z_1)}{\partial x_1} \rangle = \langle \frac{\partial f_1(z_1)}{\partial p_1} \mid \frac{\partial}{\partial x_1} \int_{T^*(\Lambda)} dz_2 f_1(z_2) V(x_1 - x_2) \rangle, \tag{1.36}$$

which can be rewritten in the following compact form:

$$\frac{\partial f_1(z_1)}{\partial t} = \left\{ f_1(z_1), \frac{\delta \tilde{\mathcal{H}}(\mathcal{F})}{\delta f_1(z_1)} \right\}^{(1)},\tag{1.37}$$

where we put, by definition,

$$\tilde{\mathcal{H}}(\mathcal{F}) := \int_{T^*(\Lambda)} dz_1 \frac{p_1^2}{2m} f_1(z_1) + \frac{1}{2} \int_{T^*(\Lambda)^2} dz_1 dz_2 V(x_1 - x_2) f_1(z_1) f_1(z_2). \tag{1.38}$$

The kinetic equation (1.36) naturally coincides exactly with that obtained before from the naively reduced evolution equation

$$\frac{\partial f_1(z_1)}{\partial t} = \left\{ \left\{ \mathcal{H}(\mathcal{F}), f_1(z_1) \right\} \right\} \Big|_{M_{\mathcal{F}}^{(1)}} \tag{1.39}$$

on the submanifold  $M_{\mathcal{F}}^{(1)} \subset M_{\mathcal{F}}$ , as it is globally invariant [18,24] with respect to the classical Lie-Poisson-Bogolubov structure

The obtained result can be formulated as the following proposition.

**Proposition 1.4** The first coorelation function Dirac type reduction on the functional submanifold  $M_{\mathcal{F}}^{(1)} \subset M_{\mathcal{F}}$ , formed by relationships (1.27), reduces the corresponding Bogolubov chain of many-particle kinetic equations to the well known classical Vlasov kinetic equation.

Remark 1.5 It is worth to mention here that the well known classical Bogolubov approximation of the many-particle distribution functions as  $f_n(z_1, z_2, ..., z_n) := \varphi_n(z_1, z_2, ..., z; f_1), z_i \in T(\Lambda), j = \overline{2, n}$ , with mapping  $\varphi_n : (...) \times M_{f_1} \to \mathbb{R}, n \in \mathbb{N} \setminus \{1\}$ , presenting smooth nonlinear functionals, independent of the temporal parameter  $t \in \mathbb{R}_+$ , define a suitably different functional submanifold  $\tilde{M}^{(1)}_{\mathcal{F}} \subset M_{\mathcal{F}}$ , upon which the reduced evolution flow

$$\frac{\partial f_1(z_1)}{\partial t} = \left\{ \left\{ \mathcal{H}(\mathcal{F}), f_1(z_1) \right\} \right\} \Big|_{M_{\mathcal{F}}^{(1)}} \tag{1.40}$$

gives rise to a new Boltzmann type kinetic equation, being compatible with evolution equations for higher distribution functions, free of evolution inconsistencies and completely different from that derived before by Bogolubov [4].

The same way as above one can explicitly construct the system of invariantly reduced kinetic equations

$$\frac{\partial f_1(z_1)}{\partial t} = \left\{ \left\{ \mathcal{H}(\mathcal{F}), f_1(z_1) \right\} \right\} \Big|_{M_{\mathcal{F}}^{(2)}}, \frac{\partial f_2(z_1, z_2)}{\partial t} = \left\{ \left\{ \mathcal{H}(\mathcal{F}), f_2(z_1, z_2) \right\} \right\} \Big|_{M_{\mathcal{F}}^{(2)}} \tag{1.41}$$

on the submanifold  $M_{\mathcal{F}}^{(2)} \subset M_{\mathcal{F}}$ , which already is not *a priori* globally invariant with respect to the Hamiltonian evolution flows on  $M_{\tau}$  and whose detail structure and analysis are postponed to another place. This cae

#### Conclusion

We studied a well known classical problem of constructing a compatible nite-particle reduction of the Bogolubov chain of manyparticle distribution functions and analyzed a special class of the related dynamical systems of BoltzmannBogolubov and Boltzmann Vlasov type on innite dimensional functional manifolds, modeling kinetic processes in many-particle media. Based on the geometric approach, e/ectively devised to studying the corresponding many-particle Lie-Poisson functional phase space, we succeeded in dual analysis of the innite Bogolubov hierarchy of many-particle distribution functions and their Hamiltonian structure. Moreover, we proposed a new an e/ective approach to invariant Dirac type reduction of the Bogolubov hierarchy upon a suitably chosen invariant Poisson subspace endowed and deduced the related modied BoltzmannBogolubov kinetic equations on a nite set of multi-particle distribution functions.

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